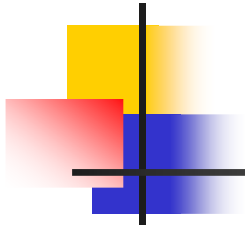




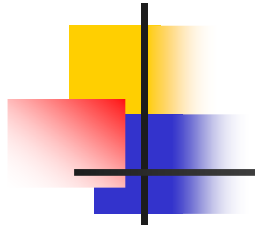
# Algorithms 2005

---

Ramesh Hariharan



# Algebraic Methods



# Principal Component Analysis

---

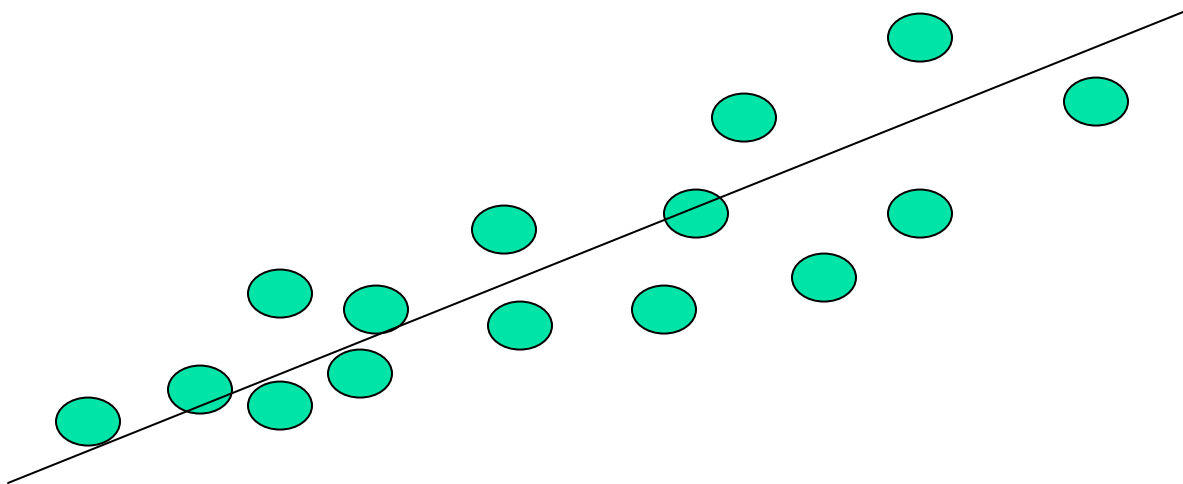
- Given  $m$  points in a  $n$  dimensional space, for large  $n$ , how does one project on to a 2 or 3 dimensional space while preserving broad trends in the data and allowing it to be visualized?



# Principal Component Analysis

---

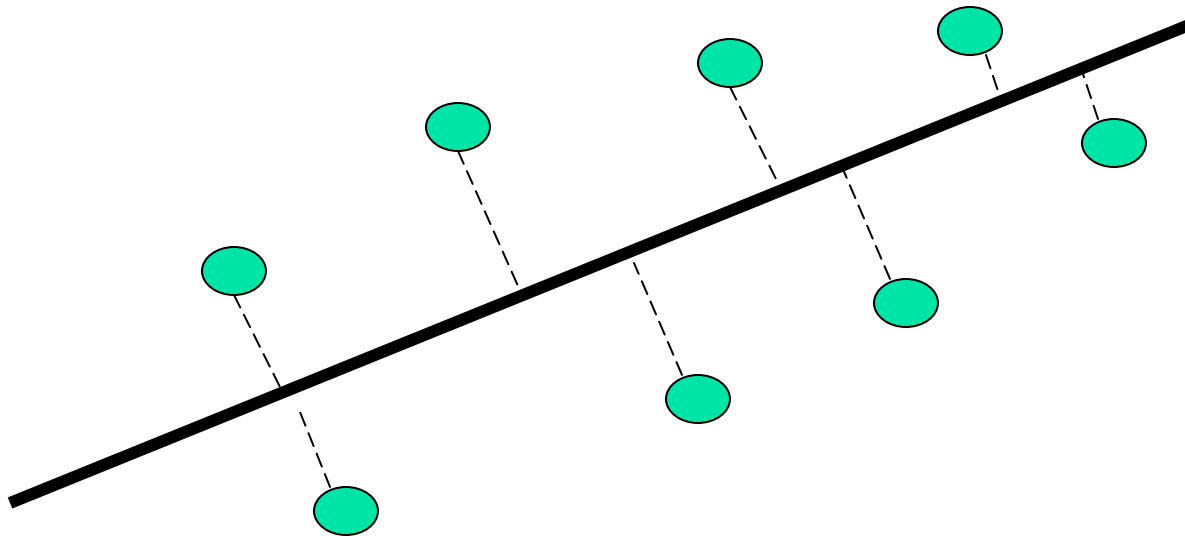
- Given  $m$  points in a  $n$  dimensional space, for large  $n$ , how does one project on to a 1 dimensional space?



- Choose a line that fits the data so the points are spread out well along the line

# Principal Component Analysis

- Formally, minimize sum of squares of distances to the line.

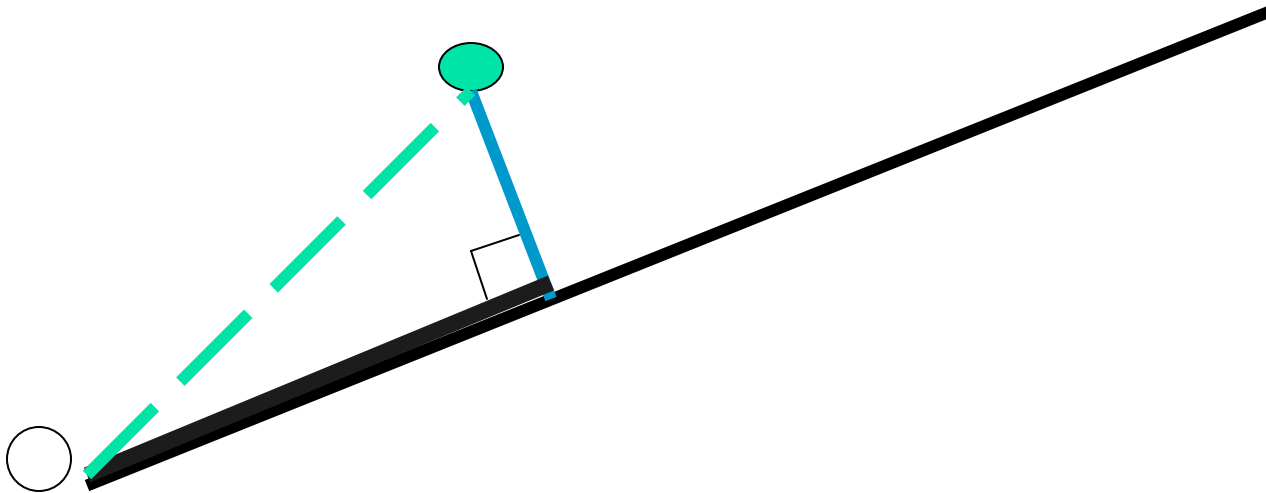


- Why sum of squares? Because it allows fast minimization, assuming the line passes thru 0



# Principal Component Analysis

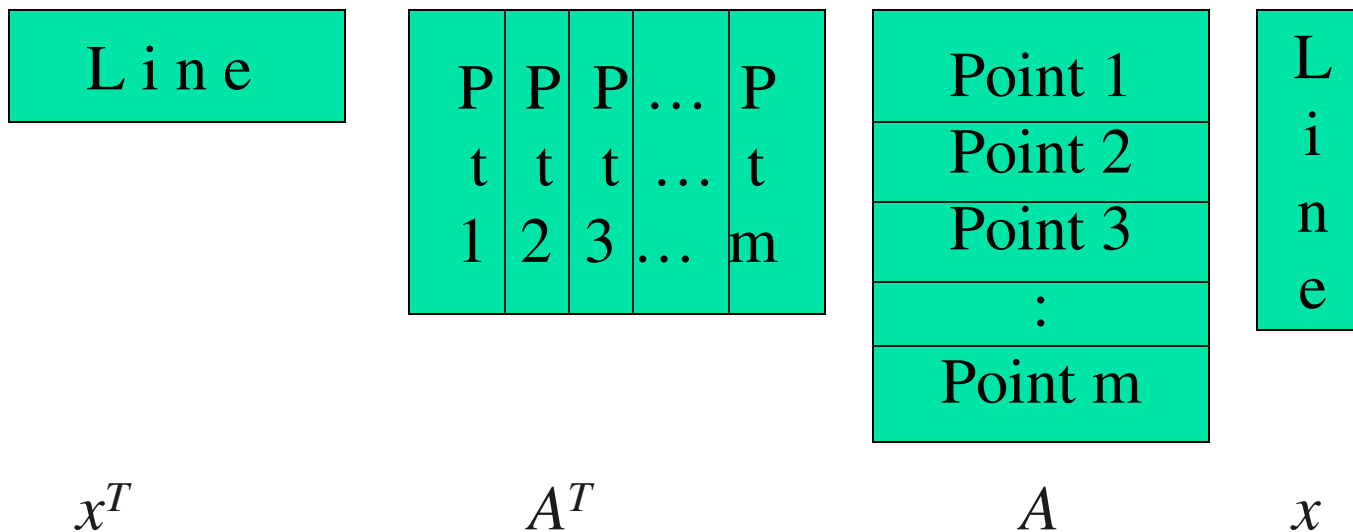
- Minimizing sum of squares of distances to the line is the same as maximizing the sum of squares of the projections on that line, thanks to Pythagoras.





# Principal Component Analysis

- How is the sum of squares of projection lengths expressed in algebraic terms?





# Principal Component Analysis

---

- How is the sum of squares of projection lengths expressed in algebraic terms?

$$\max(x^T A^T A x), \text{ subject to } x^T x = 1$$





# Principal Component Analysis

---

- Rewriting this:

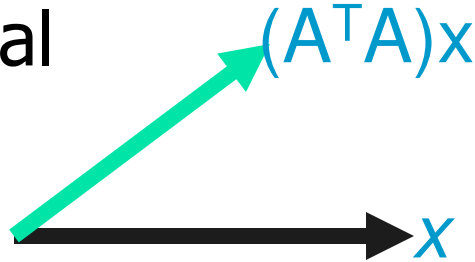
$$\begin{aligned}x^T A^T A x &= e = e x^T x = x^T (e x) \\ \Leftrightarrow x^T (A^T A x - e x) &= 0\end{aligned}$$

- Show that the maximum value of  $x^T A^T A x$  is obtained for  $x$  satisfying  $A^T A x = e x$
- So, find the largest  $e$  and associated  $x$  such that the matrix  $A^T A$  when applied to  $x$  yields a new vector which is in the same direction as  $x$ , only scaled by a factor  $e$ .



# Principal Component Analysis

- $(A^T A)x$  points in some other direction in general



$x$  is an eigenvector and  $e$  an eigenvalue if

$$ex = (A^T A)x$$


A diagram illustrating the eigenvalue case. A black arrow labeled  $x$  points horizontally to the right. A cyan arrow labeled  $ex = (A^T A)x$  also points horizontally to the right, overlapping the black arrow.



# Principal Component Analysis

---

- How many eigenvectors are there?
- For Real Symmetric Matrices
  - except in degenerate cases when eigenvalues repeat, there are  $n$  eigenvectors
    - $x_1 \dots x_n$  are the eigenvectors*
    - $e_1 \dots e_n$  are the eigenvalues*
  - all eigenvectors are mutually orthogonal and therefore form a new basis
    - Eigenvectors for distinct eigenvalues are mutually orthogonal
    - Eigenvectors corresponding to the same eigenvalue have the property that any linear combination is also an eigenvector with the same eigenvalue; one can then find as many orthogonal eigenvectors as the number of repeats of the eigenvalue.
- Show the above properties



# Principal Component Analysis

---

- For matrices of the form  $A^T A$ 
  - All eigenvalues are non-negative (show this)



# Principal Component Analysis

- How are the eigenvectors computed?

Since the eigenvectors form a basis:

$$\begin{aligned}(A^T A) y &= (A^T A) (a_1 x_1 + a_2 x_2 + \dots + a_n x_n) \\ &= a_1 e_1 x_1 + \dots + a_n e_n x_n\end{aligned}$$

$$(A^T A)(A^T A) y = a_1 e_1 e_1 x_1 + \dots + a_n e_n e_n x_n$$

- Repeated application of  $A^T A$  on almost any vector  $y$  converges to a scaled version of the eigenvector  $x_1$  corresponding to the largest eigenvalue  $e_1$ .
- $y$  should satisfy  $a_1 \neq 0$

What happens if  $e_1$  is a repeated eigen value?



# Principal Component Analysis

---

- Algorithm for computing the fitting line
  - Compute  $A^T A$
  - Start with (almost) any vector  $y$
  - Repeatedly multiply  $A^T A$  with  $y$  and rescale until convergence (in practice, a fixed number of times)
  - The resulting direction is the fitting line direction!!



# Principal Component Analysis

---

- Time taken for convergence
  - How many iterations  $i$  before
    - $[a_1(e_1)^i] / [\sum a_k(e_k)^i] > 1-\epsilon$
    - $a_1(e_1)^i \epsilon > \sum a_{k>1}(e_{k>1})^i$
    - $a_1(e_1)^i \epsilon > n a_{\max}(e_2)^i$
    - $a_1/a_{\max} (e_1/e_2)^i > n/\epsilon$
    - $i > \log(n/\epsilon a_{\max}/a_1) / \log(e_1/e_2)$



# Principal Component Analysis

---

## Optimization

- if  $A$  is  $m \times n$  and  $m \ll n$  then  $A^T A$  is  $n \times n \gg m \times m$
- use  $AA^T$  instead, eigenvector of  $AA^T$  is easily converted to that of  $A^T A$

$$(AA^T)y = e'y$$

$$\Rightarrow A^T(AA^T)y = e'(A^T y)$$

$$\Rightarrow (A^T A)(A^T y) = e'(A^T y)$$

$$\Rightarrow A^T y \text{ is the eigenvector of } A^T A$$





# Principal Component Analysis

---

- New algorithm for computing the fitting line
  - Compute  $B = A^T A$  or  $AA^T$  whichever is smaller
  - Start with (almost) any vector  $y$
  - Repeatedly multiply  $B$  with  $y$  and rescale until convergence
  - If  $B = A^T A$  then the resulting direction is the fitting line direction
  - If  $B = AA^T$  then  $A^T$  times the resulting direction is the fitting line direction



# Principal Component Analysis

---

- Complexity

- Compute  $B = A^T A$  or  $A A^T$  : (cols x rows x cols) or (rows x cols x rows), whichever is smaller
- Iterations: cols x cols x numIterations or rows x rows x numIterations, whichever is smaller
- If  $B = A A^T$  then multiplication with  $A^T$  takes cols x rows



# Principal Component Analysis

---

- The Conundrum in Practice

- For  $9000 \times 2000$ ,  $B = A^T A$  takes  $2000 \times 9000 \times 2000$
- For  $2000 \times 9000$ ,  $B = A A^T$  takes  $2000 \times 9000 \times 2000$
- Iterations:  $2000 \times 2000 \times \text{numIterations}$  in both cases
- For  $2000 \times 9000$ ,  $B = A A^T$  and multiplication with  $A^T$  takes  $2000 \times 9000$

Yet,  $9000 \times 2000$  takes 100 times what  $2000 \times 9000$  takes!!!!



# Principal Component Analysis

---

- A careful look at the code
  - *for i=0 to min(rows,cols)*
  - *for j=0 to min(rows,cols)*
  - *if rows<cols*
  - *{for k=0 to cols*
  - *B[i,j]=A[i,k]\*A[j,k]*
  - *}*
  - *else*
  - *{for k=0 to rows*
  - *B[i,j]=A[k,i]\*A[k,j]*
  - *}*



# Principal Component Analysis

---

- A careful look at the code
  - The  $AA^T$  option shows strong locality of reference
  - The  $A^T A$  option shows strong non-locality of reference
  - Caching misses cause a greater than 100 fold slowdown in the latter cache



# Principal Component Analysis

---

- The solution

- Prior to doing  $A^T A$ , move A into a linear array stored in column major order.
- Currently done using an extra array, can one save an array? More space usage is bad. **How does one convert row major to col major order in place for a rectangular matrix?**
- With this, both  $A^T A$  and  $A A^T$  take the same amount of time.



# Principal Component Analysis

---

- Further dimensions

- Once the line along which projections are made is found, all points are projected to the space orthogonal to this line to find further dimensions, recursively.
- These dimensions are called principal components; usually only a few are computed.
- The strength associated with a dimension is the corresponding eigenvalue = the sum of squares of projection lengths
- The total sum of all eigenvalues over all eigenvectors is equal to the squares of the lengths of the point vectors themselves; the strength of an eigenvalue is expressed as a fraction of this quantity.



# Principal Component Analysis

---

- Why normalize points?
  - Assumption: Fitting line passes through the origin.
  - This assumption is necessary for fast computation.
  - If data is skewed along any dimension then good fitting lines need not pass through the origin; mean centering helps reduce this skew.