



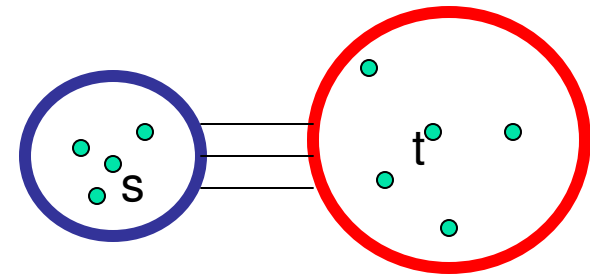
Topics in Algorithms 2005

Max Cuts

Ramesh Hariharan

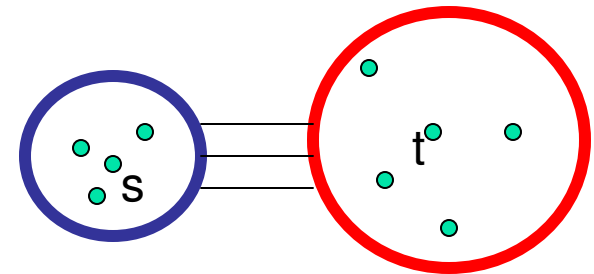
Undirected Unweighted Max Cut

- **Cut:** Partition of the vertex set
- **Max Cut:** Number of edges between the two sides of the partition should be maximized



Status

- Max Cut is NP-Complete!! Unlike Min-cut.
- If we can solve this problem we can solve the 3-SAT problem and we can solve any problem which can be solved in non-deterministic polynomial time by a Turing Machine.





NP-Completeness

Show that Max Cut is NP-Complete:

- Reduce from 3-SAT
- Given a 3-SAT formula f find a graph G and a number k such that
 - f is sat implies G has a cut of size k .
 - f is not sat implies G has no cut of size k or larger.



Reduction from 3-SAT

Reduce from 3-SAT:

- Put 2 vertices for each variable x , one for x and one for \bar{x}
 - Connect pairs of vertices x, \bar{x} by k edges
- Put one vertex for each clause
 - Connect literals in that clause to it
- The Max Cut will always split complement literal pairs why??
- Ideally, the Max Cut should now equal the number of clauses satisfied plus nk where n is number of variables
- Problems!
 - A clause could have more than 1 satisfying literal
 - Clause vertices could get split as well



Reduction from 3-SAT

Reduce from 3-SAT:

- We need to ensure that each satisfied clause contributes the exact same amount to each cut and each unsatisfied clause contributes a lesser amount. How do we ensure this??
- We need to handle splitting of clause vertices. How?

Trick

- Work with heterogeneous 3-SAT instead
- 3-SAT in which satisfiability requires the assignment to have at least one true and one false in each clause
- Heterogeneous 3-SAT is also NP-Complete. Exercise??



Reduction from hetero-3-SAT

Reduce from hetero-3-SAT with m clauses and n variables:

- Put $2m$ vertices for each variable x , m for x and m for \underline{x}
 - There are 2 vertices associated with each clause
 - Connect all m^2 pairs of vertices x, \underline{x} by k edges each forcing them to come on different sides
- For each clause
 - Connect the three literals for this clause together.
- The Max Cut is $knm^2 + 2\#\text{satisfiable clauses}$. Why??



Approximation Algorithms

- Can we find a near optimal solution in polynomial time?
- E.g., What if we take a random cut? How does it compare to the min-cut?
 - Show that the expected number of edges in the random cut is $\#edges/2$. Exercise!!
 - Thus a random cut is a expected factor $1/2$ approximation



Approximation Algorithms

- How about a greedy algorithm. Switch sides for a vertex if it improves the cut.
 - Will this terminate??
 - What approximation factor does it get??



Beating the $\frac{1}{2}$ factor

- Can you write max-cut as a linear/concave program (so local and global maxima are the same)?

$$\text{Max}_{e=(i,j)} (1-x_i \cdot x_j)/2$$

For each vertex x_i , $x_i = -1$ or $x_i = 1$

- Issues
 - Not Linear. Is the objective function concave?
 - How does one relax the $-1, 1$ constraints?
 - Linear relaxation: $x_i \geq -1$ and $x_i \leq 1$
 - How does one solve a concave problem in polynomial time?
 - How does one round linear solutions to integer solutions?



Concavity

- A twice differentiable function is concave if and only if its Hessian is negative semidefinite, i.e., for vectors v

$$\begin{matrix} \boxed{v} & \boxed{\delta^2 f / \delta x_i \delta x_j} & \boxed{v} & \leq 0 \end{matrix}$$



Maximizing Concave Functions

There are polynomial time algorithms to maximize concave function over any convex set (eg one obtained by intersection of linear inequalities)

- Reference: Solving Convex Programs by Random Walks
By Bertsimas and Vempala



Beating the $\frac{1}{2}$ factor

$$\text{Max}_{e=(i,j)} (1-x_i \cdot x_j)/2$$

For each vertex x_j , $-1 \leq x_j \leq 1$

■ Issues

- How does one round linear solutions to integer solutions?
- Think about this? Not sure what is known.



Another Relaxation

$$\text{Max}_{e=(i,j)} (1-x_i \cdot x_j)/2$$

For each vertex x_i , $-1 \leq x_i \leq 1$

- Relax x_i s to be vectors of length 1
- Issues
 - Is the feasible region convex?
 - How does one round?



SemiDefinite Formulation

$$\text{Max}_{e=(i,j)} (1-d_{ij})/2$$

$$d_{ij}$$

Is pos semidefinite

- The feasible region is convex
- The objective function is linear
- So solvable in polynomial time
- In addition, a nice geometric interpretation
- Due to Goemans and Williamson



SemiDefinite Formulation

$$\text{Max}_{e=(i,j)} (1-d_{ij})/2$$

$$d_{ij}$$

Is pos semidefinite

- Rounding
 - Solving the program yields a set of unit length vectors
 - Use a random hyperplane through the origin to split the vectors into 2; this gives a cut
 - How does the size of this cut compare to that of the semidef program optimum??



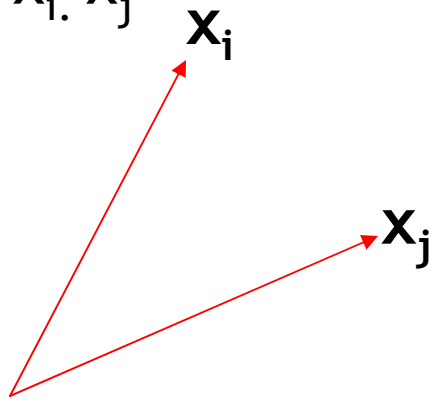
SemiDefinite Formulation

$$\text{Max}_{e=(i,j)} (1-d_{ij})/2$$

$$d_{ij}$$

Is pos semidefinite

$$d_{ij} = x_i \cdot x_j$$



- The probability of the edge e appearing in the cut is $\arccos(d_{ij})/\pi$

- So the approx factor is $2 \arccos(d_{ij})/\pi (1-d_{ij})$

- How low can $2\theta/\pi (1-\cos \theta)$ be?? Exercise??



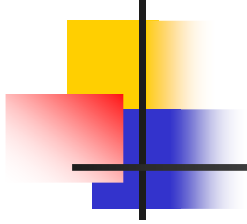
References

- Bertsimas, Vempala on convex programming
- Goemans-Williamson's paper on Max-Cut



Exercise

- Max-2-SAT
- Given a 2 SAT formula find an assignment which satisfies as many clauses as possible
- Can you give a simple randomized algorithm followed by a SemiDefinite relaxation and then Rounding algorithm?



Thank You
